



Kollisionsfreie Bahnplanung mit Rapidly exploring Random Trees (RRTs) bei mehreren Robotern (German Edition)

Thomas Neuhauser

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Bachelorarbeit, die am 18.05.2005 erfolgreich an einer Fachhochschule in Deutschland im Fachbereich Informatik eingereicht wurde. Einleitung: Überall werden in zunehmendem Maße Roboter zur Automatisierung verschiedenster Prozesse eingesetzt. Grundsätzlich

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